

64-CHANNEL PRESSURE

SCANNER SYSTEM

User Manual



WARNING

Read this document before using the product.

This is an experimental prototype, for measurement purposes only.

This system is not certified for use on aircraft.

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Version Control

Version	Date	Summary of changes
1.0	05-2017	New document
2.0	09-2019	Updated content and specifications, reformatted.
		Addition of guidance on synchronisation of multiple scanners.
2.1	01-2020	Expansion of guidance on software and drivers.
2.2	04-2020	Updated multichannel connector pin assignment.
3.0	01-2023	Updated for version 2.0 of firmware and software.
3.1	02-2023	New commands added to command string table

1 INTRODUCTION

Principle of operation

The system consists of a base unit (housing the base sensor array, the microprocessor and control hardware), a number of eight-channel pressure 'blades' designed to be self-detecting and customer-swappable, and a remote fluid temperature sensor and cable assembly. The base sensor array contains a pressure altimeter, a six-component inertial measurement unit, a case temperature sensor and a humidity sensor. The system's power and communications are all via USB.

System description

Multichannel pressure scanner system.

System components

1x Base system	The base system contains all of the control hardware to drive the pressure sensor blades.
(X) Sensor blades	The quantity and range of the sensor blades will depend on the customer order. One blade is typically included with the cost of the base system.
1x Temperature probe	A fluid temperature probe and cable assembly is included with the base system.
1x USB cable	A low-profile USB micro->A connector is bundled with the system.
Accessories	Accessories including an enclosure, pressure cables and connectors are available and may have been included in the shipment.

Please ensure that all the system components listed above have been supplied, and that there is no apparent damage from shipping.

System requirements

To interface with a computer, the scanner system requires 64-bit Windows 7 (or newer) operating system (not included). The scanner has been pre-loaded with firmware; the computer software drivers and data logging software will be provided electronically.

DETAILED SPECIFICATION 2

Product code	DPS14-160P	DPS14-1K0	DPS14-6K9		
Pressure range (custom ranges available)	160 Pa FS	1 kPa FS	6.9 kPa FS		
Maximum overpressure	33.5 kPa	37.5 kPa	69 kPa		
Sensor repeatability ¹		± 0.024 % FS			
Sensor accuracy ² , inc. calibration		± 0.25 % FS			
Total error band after auto-zero ³	± 1.75 % FS	± 0.5 % FS	± 1 % FS		
Ambient absolute pressure sensor specification	30-110 kPa FS, +/- 0.1 kPa				
Absolute pressure limits		0.2 - 1.5 atm			
Operational mode	Absolute and differential configurations available				
Operating temperature range ⁴ (extended ranges available)	-20° to +85° C non-condensing				
Compensated temperature range	0° to +50° C non-condensing				
Storage temperature range	-40° to +85° C				
Ambient temperature sensor specification	0°C - 65°C ± 0.5°C				
Remote temperature probe specification	-40°C - 150°C ± 0.5°C				
Vibration	Sensors r	ated to 15 g, 10 H	z to 2 Hz		
Maximum relative humidity		95 %			
Relative humidity sensor specification	0 %	to 100 % RH, +/- 3	3%		
Communications interface	Data streaming via USB2.0, external trigger and clock ports for scalable multi-system synchronization				
Power	via	USB, < 200 mA, 1	W		
Data acquisition rate	1 kHz s	imultaneous (equiv	valent)		
Digital resolution	14-bit pressure	e, 16-bit environme	ental and IMU		
System requirements	Windows 7 or later, minimum 3GHz & 4Gb RAM				
IMU specification	3 axis gyro 3 axis accel	, 245 °/s FS, ± 8.7 erometer, 2g FS, ±	5 x10 ⁻³ °/s - 0.061 ma		

¹ Includes errors due to pressure non-linearity, pressure hysteresis and non-repeatability.

² Includes errors due to pressure non-linearity, pressure hysteresis, non-repeatability and calibration uncertainty.
³ Total residual error after auto-zero, excluding residual temperature sensitivity.

⁴OEM configuration only. Nylon enclosure maximum temperature 65°C.

3 PHYSICAL CONNECTIONS

If the scanner was supplied in an enclosure, then all of the pressure connections have been factory-installed. In OEM configuration, the pressure ports are directly accessible, as barbs on the blade-mounted sensor units. The barbs are suitable for 1 mm ID silicone air lines.



Figure 1: System configuration

To insert a blade into the base unit, ensure that the retaining clips are in the 'open' position (pushed outward); align the blade with the socket, and apply gentle pressure to the blade card until it snaps into place. The retaining clips should toggle into the 'locked' position. An alignment tab on the socket prevents backwards insertion of the blades.

Note that sensor card slots must be filled sequentially from slot '0'. The unit will not function properly otherwise.

WARNING: Do not apply force on the sensors themselves during blade insertion or removal, or damage may result.

To remove a blade from the base unit, gently push the retaining clips outward into the 'open' position. The blade will pop out of the socket and can then be gently removed.

If the scanner was shipped in an enclosure with a multichannel connector, then the system has been factory-assembled for you. In this case, the channels are numbered as shown below.



FRONT OF UNIT

Figure 2: Multichannel connector numbering convention

	Connector marking	Channel line
	0	0
	1	0 (ref)
	2	1
	3	1 (ref)
	4	2
If using independent pressure	5	2 (ref)
	6	3
	7	3 (ref)
	REF1	NC
	REF2	NC
	0	0
	1	1
If using common pressure	2	2
reference		
	REF1	Reference 1
	REF2	Reference 2 or NC

Table 1: Multichannel connector pin assignment

4 CARE AND HANDLING

WARNING: Do not allow any electrically conductive materials to come into contact with the system, or it may be permanently damaged.

- The card is not protected with any electrically insulating coating. Do not allow any liquid onto the board. It is recommended to wear latex or similar gloves when handling the board to prevent deposits. Sensible ESD precautions should be taken before handling.
- During fitting of silicone tubing to scanner and pressure sensor ports, ensure that no dust, dirt or liquid enters the lines. This will alter the system performance. Any foreign material introduced into the sensors themselves may permanently damage the sensors.
- If not enclosed, ensure that a protective cover is placed over the system when not in use, and handle with care.
- Protect the sensors from moisture and dust, and store in an ESD-safe sleeve when not in service.
- Ensure that all electronic and pressure connections are appropriately strain-relieved.
- Do not use the pressure scanner system in wet or condensing conditions. Store in dry environment, or with desiccant pouch.

5 SOFTWARE AND DRIVERS

The system requires a USB connection with a computer in order to function.

Drivers

There are two external drivers which must be downloaded and installed on the computer in order for the PC to be able to interface with the system, in addition to the specific system driver.

- National Instruments LabView Run Time Engine (LVRTE)
- National Instruments VISA Run-Time Engine (NIVISA)

These drivers are freely available for download from National Instruments. Ensure that the 64-bit version of the Labview Runtime Engine is selected (note this is not the default option), and restart the computer following each installation. Correct download settings for each driver are shown in Figure 3 and 4 below.

The <u>Surrey Sensors Ltd. 32-bit USB driver</u> is required for USB comms. This can be freely downloaded from the product website.

Additionally, a further comms system install may be required for some older versions of Windows (not required for Windows 10).

Home > Support > Software and Driver Downloads > NI Software Product Downloads > Download Detail Page					
+	LabVIEW is systems engineering software for applications that require test, measurement, an + Read More	nd cont			
DOWNLOADS					
Supported OS	Windows View Readme				
Version	Use latest available				
Application Bitness	64-bit V				
	Note: Unless you require the additional memory provided by the 64-bit option, NI recommends that you download the 32-bit version. Learn More				
Included Editions	O Base, Full, Professional				
	Runtime				
Language 🕕	English, French, German, Japanese, Korean, Simplified Chinese				
Driver Software Included 🔘	No				

Figure 3: Download settings for NI Labview Runtime Engine

Home 〉 Support 〉 Software and [Home > Support > Software and Driver Downloads > NI Driver Downloads > Download Detail Page					
\checkmark	NI-VISA NI-VISA provides support for customers using Eth + Read More Note: Install programming environme	ernet, GPIB, serial, USB, and other types of instru ents such as NI LabVIEW or Microsoft Vis				
DOWNLOADS						
Supported OS	Windows ~	View Readme				
Version	Use latest available V					
Application Bitness	32-bit & 64-bit					
Included Editions	Full					
Language	English, French, German, Japanese, Korean, Simplified Chinese					

Figure 4: Download settings for NI VISA Runtime Engine

Executable

An executable software package is provided with your system, which facilitates direct communication with a PC using the micro-USB connector. After launching the software, you should see the window reproduced below (Figure 5).

Starting procedure

- 1) Connect the computer to the scanner's micro-USB socket.
- 2) Load the program. It will start in the [ACTION] tab.
- 3) Using the [COM PORT] drop down menu, select the appropriate COM port.
- 4) Press the white arrow near the top left corner of the window to run the application. The scanner will automatically power on.
- 5) The scanner will perform a power-on self-test, lasting a couple of seconds. During this process, the green LEDs on the sensor cards will blink, and remain on if the test is passed (these LEDs are not visible if the scanner is supplied in an enclosure).
- 6) Ensure that there are no errors in the [ERROR] dialogue box. If an error has occurred at this stage, it is most likely an invalid COM port selection. If using an older Windows version this may alternatively be a compatibility error requiring the additional installation described above.

Pressure Scanner User Interface v2.0.vi	-	
File Edit Operate Tools Window Help		Prean-64
•		panel
Action System status Auto-zero EEPROM config. Data rate Data stream B	ar graph	Paul Nathan 01/2023
COM port Command	Go	
Datalog file path (full)		
Finite samples	ata stream	
Serial number d 1064 Status code d 0 source		Exit

Figure 5: Start-up/ configuration window

Available commands

- Enable USB streaming: this command activates the USB data stream. The [DATA STREAM] tab is activated and a running plot of all pressure sensor values is displayed, along with values for other on-board sensors. This will continue indefinitely until either (a) the user presses the [STOP] button; (b) the user or selects another tab; (c) the user exits the program by closing the window, or (d) the number of samples has been acquired as specified on the action tab and the "Finite samples" function is enabled.
- Enable USB streaming (HW-Trig): this command activates the USB data stream, but instruct the system to wait for an external trigger command before beginning the acquisition.
- Get status info: running this command will activate the [SYSTEM STATUS] tab. The system will be queried for the status of the last self-test. Green indicators indicate the test was passed, while red indicates a fault. Descriptive text beside each indicator is provided.
- **Run self-test:** the system will be made to perform the power-up self-test again, and then query for the result. This allows the user to easily check any changes made without having to disconnect and reconnect the USB cable.
- **Perform temporary auto-zero:** this command activates the [AUTO ZERO] tab and begins collecting samples from each pressure sensor to estimate the zero pressure reading. An offset is then temporarily stored in volatile memory that will remain until the system is powered down or reset. During this procedure, ensure that the sensors are subjected to zero differential pressure.

- **Perform permanent auto-zero**: this command repeats the above, but this time writing the offsets permanently to non-volatile memory. *WARNING this will overwrite the existing offsets that were used during factory calibration. Carrying out this procedure may invalidate your warranty.*
- Set data rate: This command allows the user to set the system sampling rate using a drop-down menu.
- **Get data rate:** This command allows the user to retrieve the current setting of the system sampling rate.
- Get serial number: Each scanner is encoded with its own unique serial number. This function will retrieve the probe's serial number and display it in the [ACTION] tab. Note that the serial number is also retrieved as part of the normal start-up operations. The serial numbers are decimal values; the probe having serial number "1234" will display as [d1234].
- Disable USB streaming: this command stops data transmission over USB.
- **Disable HW-Trig:** this command stops data transmission over USB and disables the wait-for-trigger command.
- **Get EEPROM values:** displays the [EEPROM CONFIG] tab and read off all the EEPROM values from the system.
- Set EEPROM values: this command should not be used under normal operating circumstances, and is included for development purposes only. To make changes to the EEPROM values, first run [GET EEPROM VALUES] to populate the table with the current values. It is strongly recommended that you record and retain the factory-set values. Then, change the values as desired; return to the [ACTION] tab and run the [SET EEPROM VALUES] command. Finally, return to the [ACTION] tab and run the [GET EEPROM VALUES] command again to check the values are as desired and, importantly, that the EEPROM checksum indicator is green. A red indicator means the data has become corrupt in transit and should be re-transmitted. *WARNING this will overwrite the existing factory-set EEPROM values. Carrying out this procedure may invalidate your warranty.*
- **System soft reset:** this command restarts the system's firmware and clears any temporary auto-zero that was carried out.
- **Power OFF:** this command powers off the sensor array, and may be used to reduce the power consumption of the sensor system when not in use without physically disconnecting the pressure scanner.
- **Power ON:** this command powers on the sensor array. If the system has been powered off using the [POWER OFF] command, it must be powered on again before attempting any data acquisition or a system error will occur.
- Get sensors range and offset: this command reads and returns the ranges and offsets of each of the sensors installed in the scanner. The results will display in a window under the [SYSTEM STATUS] tab, selectable by sensor number.

• **Exit:** this command stops the program from running, but leaves the window open so as to preserve settings for later use. This has the same functionality as pressing the [EXIT] button.

Bar graph

While the unit is streaming via USB, the [BAR GRAPH] tab will display values graphically for the user, in the form of a live bar chart. Note that the controls at the bottom of the plot area allow the user to control the plotting parameters.

Data logging option:

A tab-delimited ASCII text output of a time history of all the sensor values can be saved to disk by enabling the [LOG DATA STREAM] switch on the [ACTION] tab prior to running the [ENABLE USB STREAMING] command. If the [DATALOG FILE PATH] box is left empty, the user will be prompted where to save the file. It is helpful to put a known extension on the file such as ".txt". Data is written to disk every second and stopped upon disabling USB streaming. If streaming is resumed and the filename is not changed, the user will be prompted to either replace the file or cancel. If cancel is chosen, a prompt will appear to allow a new filename to be chosen. If this is also cancelled, data streaming will begin but no log file will be created.

Source distribution

A LabVIEW source distribution is also available to download from the product website, to enable the user to integrate the pressure scanner into a National Instruments LabView VI environment.

6 SYNCHRONISATION OF MULTIPLE PRESSURE SCANNERS

Any number of pressure scanners can be tied together in order to start data acquisition simultaneously. This is achieved by making use of the green 3-way trigger I/O terminal opposite the USB connector. Since each scanner operates independently, the user is free to configure the master/slave relationship as desired. Alternatively, all pressure scanners may be configured as slaves, with the start trigger provided by a separate system altogether.

To synchronize four pressure scanners (for example) with one acting as master, the setup procedure would be as follows:

- 1. Connect all scanners to the computer via USB.
- Ascertain the COM port number of each scanner. This is done by connecting one at a time and making a note of the COM port that appears under Windows device manager. Label the scanners as appropriate.
- 3. Choose any one of these scanners to be the "master". In this example, let it be COM3. The three slaves are then COM4, COM5 and COM6.
- 4. Wire the 3-way trigger terminals as illustrated below



The trigger output from the master is tied to the input of each slave. The ground terminal inter-connections are required only if the scanners are on separate grounds. If the scanners are running off the same PC or USB hub, then this is not required.

- 5. Create four distinctly named copies of the software panel executable and run each copy
- 6. Configure the COM port and datalog directory and name for each scanner. Either use the same directory and different filenames or use the same datalog name under different directories for each scanner. For example, under the latter option this would be "C:\Datalogs\Scanner01.txt" for the master and then "C:\Datalogs\Scanner02.txt" through to "...Scanner04.txt" for the slaves. *Ensure each scanner's data filepath is unique otherwise there will be a file write access conflict.* Ensure that the "Log data stream" function is enabled.

7. Under the "Action" tab, ensure that the "Finite samples" button is enabled for all instances. Enter the required number of samples, also identical for all (though not required to be so)

Once all scanners are ready, the data acquisition starting procedure is as follow

- 1. On each of the 'slave' scanners only, select the [ENABLE USB STREAMING HW TRIG] from the command drop-down menu and click [GO]. There should be no activity on the live traces as the slaves are now ready and waiting for the trigger from the master scanner. Note that there is a 15 second window between slave activation during which the trigger signal may be received, before a timeout error occurs and the system self-resets.
- 2. On the master scanner instance select the [ENABLE USB STREAMING] from the command drop-down menu and click [GO]. The live traces for each scanner should now commence simultaneously. Data will stop streaming after the specified number of samples has been acquired, or if the "Stop" button is pressed on a given scanner instance. The scanners can all be manually stopped by going through each instance and clicking the [STOP] button.

Repeat the above two steps for all future data acquisition cycles. Once the measurement is complete, the end-user can then combine the data from each scanner using their method of choice. The datalog directory and/or names can be changed and new measurements carried out as desired.

The modular nature of this system ensures that should one or more scanners suffer an error during a protracted measurement campaign, the data from the others will not be affected.

7 TECHNICAL SUPPORT

Full technical support is available for this product and its associated software.

If you experience any difficulty in installation or use, or if you need additional support in the operation of the system, please contact your Surrey Sensors Ltd. account manager or technical representative.

APPENDIX: ADDITIONAL COMMUNICATIONS DETAILS

Command string table

Comma	and string	Data string	Command description	Additional information
ASCII	HEX	-		
@P	0x4050		Power on the sensor array	
@p	0x4070		Power off the sensor array	
@D	0x4044		Start data streaming over USB	See "Serial data table.xlsx" for data format
@d	0x4064		Stop data streaming over USB	
@H	0x4048		Enable hardware trigger for data streaming start	
@h	0x4068		Disable hardware trigger for data streaming start	
@F	0x4046	float32 Data_period	Set serial data period (ms)	
@f	0x4066		Get serial data period (ms)	Returns float32 Data_period (4 bytes)
@N	0x404E		Get device serial number	Returns uint32 Serial_number (4 bytes)
@z	0x407A		Perform temporary auto-zero	Returns 64x float32 Sensor_offset (256 bytes). Offsets are restored to calibration defaults after system reset or power cycle
@S	0x4053		Run self-test and return system status bytes	Returns 17x uint8 Status_byte (17 bytes). See "Status bytes table.xlsx" for status byte formats
@s	0x4073		Return system status bytes only	Returns 17x uint8 Status_byte (17 bytes). See "Status bytes table.xlsx" for status byte formats
@W	0x4057		Get all sensors range and offset	Returns 3x float32 {P_min, P_max,P_offset} for each sensor (3 * 4 * 64 = 768 bytes)
		uint8		
@0	0x404F	N_active	Override number of active sensors	Only use the first N sensors in the array (sequential)
@R	0x4052		System reset	

All data string values, sent and received, are in Little-Endian byte order (least significant byte first). For example, the command to start data streaming over USB, '@D': the '@' char is sent first followed by the 'D' char. Alternatively in HEX format, the 0x40 byte is sent first followed by the 0x44 byte. Similarly, the command to set the serial data period to 10000 ms (100 Hz) would be, in HEX format bytes sending order left to right: {0x40, 0x46, 0x00, 0x40, 0x1C, 0x46}.

Serial data table

Byte index	Description	Туре	Unit
0	Frame character '#'	uint8	-
1			
2	DO	float32	Pa
3	FU	lioatoz	га
4			
5			
6	P1	float32	Pa
7		noutoz	1 G
8			
9			
10	P2	float32	Pa
11	. –		
12			
13			
14	P3	float32	Ра
15			
16			
17			
18	P4	float32	Ра
19			
20			
21			
22	P5	float32	Ра
23			
24			
25			
20	P6	float32	Ра
28			
29			
30			
31	P7	float32	Pa
32			
33			
34	50	a	
35	P8	float32	Ра
36			
37			
38	DO	flagtoo	D-
39	РУ	1108132	Ра
40			
41			
42	D10	float32	Da
43	ΓIV	nualoz	га
44			

Byte index	Description	Туре	Unit	
153		floot22		
154	D20		Po	
155	F30	noatsz	Ра	
156				
157				
158	P39	float32	Pa	
159	1.00			
160				
161				
162	P40	float32	Pa	
163		_		
164				
165				
100	P41	float32	Pa	
169				
160				
170				
170	P42	float32	Pa	
172				
173				
174			_	
175	P43	float32	Pa	
176				
177				
178	D44	fleet20	De	
179	P44	IIUaloz	Ра	
180				
181				
182	P45	float32	Pa	
183		noutor		
184				
185				
186	P46	float32	Pa	
187				
188				
189				
190	P47	float32	Pa	
100				
192				
104				
194	P48	float32	Pa	
195				
197	P49	float32	Pa	

45				19	98	
46	D 44	fl +00	D.	19	99	
47	P11	float32	Ра	20	00	
48				20	01	-
49				20	02	
50	5.40		_	20	03	
51	P12	float32	Ра	20	04	
52				20	05	-
53				20	06	
54	D 40	fl +00	D.	20	07	
55	P13	float32	Ра	20	08	
56				20	09	
57				21	10	
58	D 44	fl +00	D.	21	11	
59	P14	float32	Ра	21	12	
60				2 [.]	13	-
61				21	14	
62	DAG	fl +00	D.	21	15	
63	P15	float32	Ра	2	16	
64				2 [.]	17	
65				2	18	
66	D16	fleet20	De	2	19	
67	P16	fioat32	Ра	22	20	
68				2	21	-
69				22	22	
70	D47	float32	Pa	22	23	
71	PI/			22	24	
72				2	25	-
73				22	26	
74	D19	float32	Pa	22	27	
75	FIO			22	28	
76				22	29	
77				23	30	
78	P10	float32	Pa	23	31	
79	115	noatoz	га	23	32	
80				23	33	
81			Pa	23	34	
82	P20	float32		23	35	
83	1 20	noutoz	1 a	23	36	
84				23	37	
85				23	38	
86	P21	float32	Pa	23	39	
87		noutoz		24	40	
88				24	41	
89				24	42	
90	P22	float32	Pa	24	43	
91		ACCE -		24	44	
92				24	45	
93	P23	float32	Pa	24	46	

198			
199			
200			
201			
202	P50	float32	Pa
203		noutoz	1 G
204			
205			
206	P51	float32	Pa
207			
208			
209			
210	P52	float32	Pa
211	-	_	
212			
213	-		
214	P53	float32	Ра
215			
216			
217			
218	P54	float32	Ра
219	-		
220			
221	-		
222	P55	float32	Ра
223			
224			
225			
220	P56	float32	Pa
227			
220			
229	-		
230	P57	float32	Pa
232			
233			
234			
235	P58	float32	Pa
236	1		
237			
238	b =-		
239	P59	float32	Ра
240			
241			
242		fl 100	
243	P60	tioat32	Ра
244	1		
245	DC1	flag 100	
246	P61	fioat32	Ра

94			
95			
96			
97			
98			
99	P24	float32	Pa
100			
101			
102			
102	P25	float32	Ра
103			
104			
105			
100	P26	float32	Pa
107			
108			
109			
110	P27	float32	Pa
111			
112			
113			
114	P28	float32	Pa
115			
116			
117		float32	Pa
118	P29		
119			
120			
121		float32	Pa
122	P30		
123			
124			
125			
126	P31	float32	Ра
127	-		
128			
129			
130	P32	float32	Ра
131			
132			
133			
134	P33	float32	Pa
135	1.00		. ч
136			
137			
138	D31	float32	Pa
139	г 04	float32	га
140			
141	D95	floataa	De
142	F35	lioat32	Ра

247			
248			
249			
250	P62	float32	Pa
251	1.02	noutoz	ГЦ
252			
253			
254	D63	float32	Pa
255	1.00	noutoz	ГЦ
256			
257			
258	External thermistor	float32	°C
259	temperature	noatoz	Ŭ
260			
261			
262	Atmospheric	float32	Pa
263	pressure	noutoz	14
264			
265			
266	Relative humidity	float32	%
267		noutoz	70
268			
269			
270	On-board	float32	°C
271	temperature	noatoz	U
272			
273			
274	Accelerometer x	float32	a
275	component	noutoz	9
276			
277			
278	Accelerometer y	float32	а
279	component	noutoz	9
280			
281			
282	Accelerometer z	float32	a
283	component		9
284			ļ
285			
286	Gyroscope x	float32	deg /
287	component		S
288			ļ
289			
290	Gyroscope y	float32	deg /
291	component		S
292			
293	Gyroscope z		dea /
294	component	float32	s
295			-

143			
144			
145			
146	Dae	fleet20	De
147	P30	1108132	Ра
148			
149			
150	P37	float32	Pa
151			
152			

296			
297	Bank 0 (P0P7) status bits*	uint8	-
298	Bank 1 (P8P15) status bits	uint8	-
299	Bank 2 (P16P23) status bits	uint8	-
300	Bank 3 (P24P31) status bits	uint8	-
301	Bank 4 (P32P39) status bits	uint8	-
302	Bank 5 (P40P47) status bits	uint8	-
303	Bank 6 (P48P55) status bits	uint8	-
304	Bank 7 (P56P63) status bits	uint8	-
305	Clock drift warning**	uint8	-
306 307	CRC16-CCITT***	uint16	-

Byte order is little-endian (least significant byte first).

* For each bit: 0 = good data, 1 = stale data, >1 = sensor fault.

** 0 = good data, 1 = clock drift detected.

*** CRC16-CCITT 0x1021 polynomial. Initial value = 0xFFFF.

Status bytes table

Byte index	Bit	Description	Info
0	0	Sensor array power on	1 yes, 0 no
	1	MCU EEPROM checksum good	1 yes, 0 no
	2	External thermistor value in range	1 yes, 0 no
	3	IMU ident detected	1 yes, 0 no
	4	IMU accelerometer self-test pass	1 yes, 0 no
	5	IMU gyroscope self-test pass	1 yes, 0 no
	6	Environmental sensor ident detected	1 yes, 0 no
	7	0	-
	0	Pressure sensor 0 present	1 yes, 0 no
	1	Pressure sensor 1 present	1 yes, 0 no
	2	Pressure sensor 2 present	1 yes, 0 no
1	3	Pressure sensor 3 present	1 yes, 0 no
I	4	Pressure sensor 4 present	1 yes, 0 no
	5	Pressure sensor 5 present	1 yes, 0 no
	6	Pressure sensor 6 present	1 yes, 0 no
	7	Pressure sensor 7 present	1 yes, 0 no
	0	Pressure sensor 8 present	1 yes, 0 no
	1	Pressure sensor 9 present	1 yes, 0 no
	2	Pressure sensor 10 present	1 yes, 0 no
2	3	Pressure sensor 11 present	1 yes, 0 no
Z	4	Pressure sensor 12 present	1 yes, 0 no
	5	Pressure sensor 13 present	1 yes, 0 no
	6	Pressure sensor 14 present	1 yes, 0 no
	7	Pressure sensor 15 present	1 yes, 0 no
	0	Pressure sensor 16 present	1 yes, 0 no
	1	Pressure sensor 17 present	1 yes, 0 no
	2	Pressure sensor 18 present	1 yes, 0 no
2	3	Pressure sensor 19 present	1 yes, 0 no
3	4	Pressure sensor 20 present	1 yes, 0 no
	5	Pressure sensor 21 present	1 yes, 0 no
	6	Pressure sensor 22 present	1 yes, 0 no
	7	Pressure sensor 23 present	1 yes, 0 no
	0	Pressure sensor 24 present	1 yes, 0 no
	1	Pressure sensor 25 present	1 yes, 0 no
	2	Pressure sensor 26 present	1 yes, 0 no
4	3	Pressure sensor 27 present	1 yes, 0 no
4	4	Pressure sensor 28 present	1 yes, 0 no
	5	Pressure sensor 29 present	1 yes, 0 no
	6	Pressure sensor 30 present	1 yes, 0 no
	7	Pressure sensor 31 present	1 yes, 0 no
	0	Pressure sensor 32 present	1 yes, 0 no
5	1	Pressure sensor 33 present	1 yes, 0 no
	2	Pressure sensor 34 present	1 yes, 0 no

	3	Pressure sensor 35 present	1 ves 0 no
	4	Pressure sensor 36 present	1 yes 0 no
	5	Pressure sensor 37 present	1 ves. 0 no
	6	Pressure sensor 38 present	1 yes, 0 no
	7	Pressure sensor 39 present	1 yes, 0 no
	0	Pressure sensor 40 present	1 yes, 0 no
	1	Pressure sensor 41 present	1 yes, 0 no
	2	Pressure sensor 42 present	1 yes, 0 no
6	3	Pressure sensor 43 present	1 yes, 0 no
0	4	Pressure sensor 44 present	1 yes, 0 no
	5	Pressure sensor 45 present	1 yes, 0 no
	6	Pressure sensor 46 present	1 yes, 0 no
	7	Pressure sensor 47 present	1 yes, 0 no
	0	Pressure sensor 48 present	1 yes, 0 no
	1	Pressure sensor 49 present	1 yes, 0 no
	2	Pressure sensor 50 present	1 yes, 0 no
7	3	Pressure sensor 51 present	1 yes, 0 no
-	4	Pressure sensor 52 present	1 yes, 0 no
	5	Pressure sensor 53 present	1 yes, 0 no
	6	Pressure sensor 54 present	1 yes, 0 no
	7	Pressure sensor 55 present	1 yes, 0 no
	0	Pressure sensor 56 present	1 yes, 0 no
	1	Pressure sensor 57 present	1 yes, 0 no
	2	Pressure sensor 58 present	1 yes, 0 no
8	3	Pressure sensor 59 present	1 yes, 0 no
	4	Pressure sensor 61 present	1 yes, 0 no
	6	Pressure sensor 62 present	1 yes, 0 no
	7	Pressure sensor 63 present	1 yes, 0 no
	0	Pressure sensor () self-test pass	1 yes, 0 no
	1	Pressure sensor 1 self-test pass	1 yes, 0 no
	2	Pressure sensor 2 self-test pass	1 yes 0 no
	3	Pressure sensor 3 self-test pass	1 ves. 0 no
9	4	Pressure sensor 4 self-test pass	1 ves. 0 no
	5	Pressure sensor 5 self-test pass	1 yes, 0 no
	6	Pressure sensor 6 self-test pass	1 yes, 0 no
	7	Pressure sensor 7 self-test pass	1 yes, 0 no
	0	Pressure sensor 8 self-test pass	1 yes, 0 no
	1	Pressure sensor 9 self-test pass	1 yes, 0 no
	2	Pressure sensor 10 self-test pass	1 yes, 0 no
10	3	Pressure sensor 11 self-test pass	1 yes, 0 no
10	4	Pressure sensor 12 self-test pass	1 yes, 0 no
	5	Pressure sensor 13 self-test pass	1 yes, 0 no
-	6	Pressure sensor 14 self-test pass	1 yes, 0 no
	7	Pressure sensor 15 self-test pass	1 yes, 0 no
11	0	Pressure sensor 16 self-test pass	1 yes, 0 no
	1	Pressure sensor 17 self-test pass	1 yes, 0 no

l	2	Procedure concer 19 celf test pass	1,000,0,00
	2	Pressure sensor 10 self-test pass	
	 _∧	Pressure sensor 19 self-test pass	
	4	Pressure sensor 20 self-test pass	Tyes, 0 no
	5	Pressure sensor 21 self-test pass	1 yes, 0 no
	6	Pressure sensor 22 self-test pass	1 yes, 0 no
	7	Pressure sensor 23 self-test pass	1 yes, 0 no
	0	Pressure sensor 24 self-test pass	1 yes, 0 no
	1	Pressure sensor 25 self-test pass	1 yes, 0 no
	2	Pressure sensor 26 self-test pass	1 yes, 0 no
12	3	Pressure sensor 27 self-test pass	1 yes, 0 no
12	4	Pressure sensor 28 self-test pass	1 yes, 0 no
	5	Pressure sensor 29 self-test pass	1 yes, 0 no
	6	Pressure sensor 30 self-test pass	1 yes, 0 no
	7	Pressure sensor 31 self-test pass	1 yes, 0 no
	0	Pressure sensor 32 self-test pass	1 yes, 0 no
	1	Pressure sensor 33 self-test pass	1 yes, 0 no
	2	Pressure sensor 34 self-test pass	1 yes, 0 no
4.0	3	Pressure sensor 35 self-test pass	1 yes, 0 no
13	4	Pressure sensor 36 self-test pass	1 yes, 0 no
	5	Pressure sensor 37 self-test pass	1 ves. 0 no
	6	Pressure sensor 38 self-test pass	1 ves. 0 no
	7	Pressure sensor 39 self-test pass	1 ves 0 no
	0	Pressure sensor 40 self-test pass	1 yes 0 no
	1	Pressure sensor 41 self-test pass	1 yes 0 no
	2	Pressure sensor 42 self-test pass	1 ves 0 no
	- 3	Pressure sensor 43 self-test pass	1 yes 0 no
14	4	Pressure sensor 44 self-test pass	1 yes 0 no
	5	Pressure sensor 45 self-test pass	1 yes 0 no
	6	Pressure sensor 46 self-test pass	1 yes, 0 no
	7	Pressure sensor 47 self-test pass	
	0	Prossure sensor 48 self-test pass	1 yes, 0 no
	1	Pressure sensor 40 self-test pass	1 yes, 0 no
	ן ר	Pressure sensor 50 self test pass	
	2	Pressure sensor 50 self-test pass	
15	 	Pressure sensor 51 self-test pass	
	4	Pressure sensor 52 self-test pass	
	5	Pressure sensor 53 self-test pass	Tyes, 0 no
	6	Pressure sensor 54 self-test pass	1 yes, 0 no
	7	Pressure sensor 55 self-test pass	1 yes, 0 no
16	0	Pressure sensor 56 self-test pass	1 yes, 0 no
	1	Pressure sensor 57 self-test pass	1 yes, 0 no
	2	Pressure sensor 58 self-test pass	1 yes, 0 no
	3	Pressure sensor 59 self-test pass	1 yes, 0 no
	4	Pressure sensor 60 self-test pass	1 yes, 0 no
	5	Pressure sensor 61 self-test pass	1 yes, 0 no
	6	Pressure sensor 62 self-test pass	1 yes, 0 no
	7	Pressure sensor 63 self-test pass	1 yes, 0 no

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