ANALOGUE 'NANO-CTA' THERMAL ANEMOMETRY SENSOR



This ultra-miniaturized, analogue thermal anemometer uses proprietary CMOS sensor technology to measure velocities in real-time at speeds down to 10 mm/s.

- Ultralow velocity range: reliable measurement of speeds in air below 10 mm/s
- Robust, abrasion-resistant permanent sensing element
- Ultra-low calibration drift
- Analogue-balance temperature compensation system
- Surface array mountings available for high-resolution, nonintrusive measurement of wall velocities





"nano-CTA" sensing element

• See our 'nano-CTA array system' for digital version with data acquisition unit with software and drivers supplied for plug-and-play USB operation

Specification

Velocity range ¹	10 mm/s – 100m/s		
Uncertainty	± 1 % relative		
Compensated temperature range ²	0° to 70° C ambient for dry air		
Calibration drift	< 2 % over long periods of use or storage		
Storage temperature range	-40° to +85° C		
Maximum relative humidity	95 %		
Supply voltage V _{dd}	Min. 7 VDC	Typ. 15 VDC	Max. 36 VDC
Power	Min. 12mA at V_{dd} = 15 VDC		
Output analogue signal range	0 - V _{dd}		
Connector type	4-way Molex Pico-lock (Molex PN 15131-040x)		
Physical dimensions	Sensor package approx. 10 mm x 20 mm		

1- Custom extended range available

2- Using our analogue-balance temperature compensation system, available via LabVIEW DLL

Additional custom modifications available

- Custom enclosure design service available
- Range of prong diameters and lengths available
- Waterproof Parylene-coated sensors available, allowing operation in conductive media, seawater and other corrosive or harsh environments
- Extended product support and warranty available

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Dimensions



Connector Terminal Description

There are four pins: V+ (1), GND (2), Vb (3) and Vc (4), where pin 1 is on the left with the board facing upwards.



1	V+	Supply Voltage. Recommended 15 VDC for typical application. Absolute maximum 36 VDC.
2	GND	Common ground, 0V.
3	Vb	Signal voltage (raw). The measurement variable of interest.
4	Vc	Compensation voltage (raw). Used for temperature corrections.

Note the connector terminal labels are written on the reverse side of the board.

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Temperature compensation

This sensing system includes an analogue temperature compensation system. A temperature-independent output variable *X* is obtained as

$$X = V_b V_c - V_c^2$$

where V_b and V_b are the analogue voltage outputs. The variable *X* (having units of volts²) will be a function of fluid velocity only for a given fluid, and can be calibrated as required. Note that the calibration and the operating temperature range may vary with the fluid properties.

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